

$$1a) \left. \begin{aligned} \frac{\partial}{\partial y} (x^2 - 2y) &= -2 \\ \frac{\partial}{\partial x} (-2x) &= -2 \end{aligned} \right\} du_a \text{ exact}$$

$$\left. \begin{aligned} \frac{\partial}{\partial y} (y^2) &= 2y \\ \frac{\partial}{\partial x} (-2x) &= -2 \end{aligned} \right\} du_b \text{ not exact}$$

$$b) u_a = \frac{1}{3}x^3 - 2xy + \text{const}$$

$$c) \frac{u_a}{(1)} : \left. \begin{aligned} \int_{(0,0)}^{(2,0)} du_a &= \int_0^2 dx (x^2 - 2y) \Big|_{y=0} = \frac{1}{3}x^3 \Big|_0^2 = \frac{8}{3} \\ \int_{(2,0)}^{(2,2)} du_a &= \int_0^2 dy (-2x) \Big|_{x=2} = -8 \end{aligned} \right\} -\frac{16}{3}$$

$$\int_{(0,0)}^{(0,2)} du_a = \int_0^2 dy (-2x) \Big|_{x=0} = 0$$

$$\int_{(0,2)}^{(2,2)} du_a = \int_0^2 dx (x^2 - 2y) \Big|_{y=2} = \frac{8}{3} - 8 = -\frac{16}{3} \left. \vphantom{\int_{(0,2)}^{(2,2)} du_a} \right\} -\frac{16}{3}$$

\Rightarrow Both paths give same result

$$\underline{u_3} : \left. \begin{array}{l} \int_{(0,0)}^{(2,0)} du_3 = \int_0^2 dx y^2 \Big|_{y=0} = 0 \\ \int_{(2,0)}^{(2,2)} du_3 = \int_0^2 dy (-2x) \Big|_{x=2} = -8 \end{array} \right\} -8$$

$$\left. \begin{array}{l} \int_{(0,0)}^{(0,2)} du_3 = \int_0^2 dy (-2x) \Big|_{x=0} = 0 \\ \int_{(0,2)}^{(2,2)} du_3 = \int_0^2 dx y^2 \Big|_{y=2} = 8 \end{array} \right\} +8$$

the two paths give different results

$$2 a) \quad \bar{I}_a = \int_0^{\infty} dx \times \delta(e^{-x} - z)$$

$$e^{-x_0} = z \quad \Rightarrow \quad x_0 = -\ln z < 0$$

Outside of integration interval

$$\bar{I}_a = 0$$

$$2 b) \quad \bar{I}_b = \int_{-\infty}^{\infty} dx \cos(\pi x) \delta(1-x^2)$$

$$x_0^2 = 1 \quad \Rightarrow \quad x_0 = \pm 1$$

$$\text{use } \delta(f(x)) = \sum_{\text{zeros}} \delta(x-x_0) / |f'(x_0)|$$

$$\text{here } f(x) = 1-x^2 \quad f'(x) = -2x$$

$$\bar{I}_b = \cos(\pi) / |-2| + \cos(-\pi) / |2| = -1$$

3.) Derive general result for Gaussian integral

$$\underline{I} = \int d^d x \quad e^{-\vec{x}^T \underline{M} \vec{x} - 2 \vec{b} \cdot \vec{x}}$$

with symmetric matrix \underline{M} and d-vector \vec{b}

substitute $\vec{x} = \vec{y} - \underline{M}^{-1} \vec{b}$

$$\begin{aligned} +\vec{x}^T \underline{M} \vec{x} + 2 \vec{b} \cdot \vec{x} &= \vec{y}^T \underline{M} \vec{y} - \vec{b}^T \underline{M}^{-1} \underline{M} \vec{y} \\ &\quad - \vec{y}^T \underline{M} \underline{M}^{-1} \vec{b} + \vec{b}^T \underline{M}^{-1} \underline{M} \underline{M}^{-1} \vec{b} \\ &\quad + 2 \vec{b} \cdot \vec{y} - 2 \vec{b}^T \underline{M}^{-1} \vec{b} \\ &= \vec{y}^T \underline{M} \vec{y} - \vec{b}^T \underline{M}^{-1} \vec{b} \end{aligned}$$

$$\underline{I} = \int d^d y \quad e^{-\vec{y}^T \underline{M} \vec{y} + \vec{b}^T \underline{M}^{-1} \vec{b}}$$

$$= e^{\vec{b}^T \underline{M}^{-1} \vec{b}} \prod_{\nu=1}^d \sqrt{\frac{\pi}{\lambda_{\nu}}} \leftarrow \text{eigen values of } \underline{M}$$

Here : $\underline{M} = \begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix}$, $\vec{b} = \begin{pmatrix} -Ak \\ -Bk \end{pmatrix}$

eigen vectors $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \lambda_1 = \frac{1}{2}$

$\begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad \lambda_2 = \frac{3}{2}$

$$M^{-1} = \frac{1}{3} \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix}$$

check

$$\begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} = \begin{pmatrix} 3 & 0 \\ 0 & 3 \end{pmatrix} \quad \checkmark$$

$$I = e^{-\frac{1}{12} \begin{pmatrix} A \\ B \end{pmatrix}^T \begin{pmatrix} 4 & 2 \\ 2 & 4 \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix}}$$

$$\frac{\pi}{\sqrt{\frac{1}{2} \cdot \frac{3}{2}}}$$

$$I = e^{-\frac{1}{3} (A^2 + B^2 + AB)} \frac{2}{\sqrt{3}} \pi$$

Problem 4:

- a) not in equilibrium, not in steady state
- b) equilibrium
- c) nonequilibrium steady state (almost)
- d) not in equilibrium, not in steady state
(for large-scale properties approximately in nonequilibrium steady state)
- e) equilibrium
- f) nonequilibrium steady state